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# **Adafruit74HC595 Library Documentation**

***Release 1.0***

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CircuitPython driver for 74HC595 shift register.



# CHAPTER 1

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## Dependencies

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This driver depends on:

- Adafruit CircuitPython
- Bus Device

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the [Adafruit library and driver bundle](#).



# CHAPTER 2

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## Installing from PyPI

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On supported GNU/Linux systems like the Raspberry Pi, you can install the driver locally [from PyPI](#). To install for current user:

```
pip3 install adafruit-circuitpython-74hc595
```

To install system-wide (this may be required in some cases):

```
sudo pip3 install adafruit-circuitpython-74hc595
```

To install in a virtual environment in your current project:

```
mkdir project-name && cd project-name  
python3 -m venv .env  
source .env/bin/activate  
pip3 install adafruit-circuitpython-74hc595
```



# CHAPTER 3

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## Usage Example

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```
import board
import adafruit_74hc595
import busio
import digitalio
import time

spi = busio.SPI(board.SCK, MOSI=board.MOSI)

latch_pin = digitalio.DigitalInOut(board.D5)
sr = adafruit_74hc595.ShiftRegister74HC595(spi, latch_pin)

pin1 = sr.get_pin(1)

while True:
    pin1.value = True
    time.sleep(1)
    pin1.value = False
    time.sleep(1)
```



# CHAPTER 4

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## Contributing

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Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.



# CHAPTER 5

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## Documentation

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For information on building library documentation, please check out [this guide](#).



# CHAPTER 6

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## Table of Contents

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### 6.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/74hc595\_simpletest.py

```
1 import time
2 import board
3 import busio
4 import digitalio
5 import adafruit_74hc595
6
7 spi = busio.SPI(board.SCK, MOSI=board.MOSI)
8
9 latch_pin = digitalio.DigitalInOut(board.D5)
10 sr = adafruit_74hc595.ShiftRegister74HC595(spi, latch_pin)
11
12 pin1 = sr.get_pin(1)
13
14 while True:
15     pin1.value = True
16     time.sleep(1)
17     pin1.value = False
18     time.sleep(1)
```

### 6.2 adafruit\_74hc595

CircuitPython driver for 74HC595 shift register.

- Author(s): Kattni Rembor, Tony DiCola

## 6.2.1 Implementation Notes

### Hardware:

“\* 74HC595 Shift Register - 3 pack”

### Software and Dependencies:

- Adafruit CircuitPython firmware for the supported boards: <https://github.com/adafruit/circuitpython/releases>
- Adafruit’s Bus Device library: [https://github.com/adafruit/Adafruit\\_CircuitPython\\_BusDevice](https://github.com/adafruit/Adafruit_CircuitPython_BusDevice)

**class** adafruit\_74hc595.**DigitalInOut** (*pin\_number*, *shift\_register\_74hc595*)

Digital input/output of the 74HC595. The interface is exactly the same as the `digitalio.DigitalInOut` class, however note that by design this device is OUTPUT ONLY! Attempting to read inputs or set direction as input will raise an exception.

#### **direction**

Direction can only be set to OUTPUT.

#### **pull**

Pull-up/down not supported, return None for no pull-up/down.

#### **switch\_to\_input** (\*\*kwargs)

`switch_to_input` is not supported.

#### **switch\_to\_output** (*value=False*, \*\*kwargs)

DigitalInOut `switch_to_output`

#### **value**

The value of the pin, either True for high or False for low.

**class** adafruit\_74hc595.**ShiftRegister74HC595** (*spi*, *latch*)

Initialise the 74HC595 on specified SPI bus.

#### **get\_pin** (*pin*)

Convenience function to create an instance of the `DigitalInOut` class pointing at the specified pin of this 74HC595 device .

#### **gpio**

The raw GPIO output register. Each bit represents the output value of the associated pin (0 = low, 1 = high).

# CHAPTER 7

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