
AdafruitDS18X20 Library Documentation

Release 1.0

Carter Nelson

Oct 21, 2019

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CircuitPython driver for Dallas 1-Wire temperature sensor.

CHAPTER 1

Dependencies

This driver depends on:

- Adafruit CircuitPython
- Adafruit OneWire

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the Adafruit library and driver bundle.

CHAPTER 2

Usage Example

```
import board
from adafruit_onewire.bus import OneWireBus
from adafruit_ds18x20 import DS18X20
ow_bus = OneWireBus(board.D2)
ds18 = DS18X20(ow_bus, ow_bus.scan()[0])
ds18.temperature
```


CHAPTER 3

Contributing

Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.

CHAPTER 4

Building locally

To build this library locally you'll need to install the `circuitpython-build-tools` package.

```
python3 -m venv .env
source .env/bin/activate
pip install circuitpython-build-tools
```

Once installed, make sure you are in the virtual environment:

```
source .env/bin/activate
```

Then run the build:

```
circuitpython-build-bundles --filename_prefix adafruit-circuitpython-ds18x20 --
˓→library_location .
```

4.1 Sphinx documentation

Sphinx is used to build the documentation based on rST files and comments in the code. First, install dependencies (feel free to reuse the virtual environment from above):

```
python3 -m venv .env
source .env/bin/activate
pip install Sphinx sphinx-rtd-theme
```

Now, once you have the virtual environment activated:

```
cd docs
sphinx-build -E -W -b html . _build/html
```

This will output the documentation to `docs/_build/html`. Open the `index.html` in your browser to view them. It will also (due to `-W`) error out on any warning like Travis will. This is a good way to locally verify it will pass.

CHAPTER 5

Table of Contents

5.1 Simple test

Ensure your device works with these simple tests.

Listing 1: examples/ds18x20_simpletest.py

```
1 # Simple demo of printing the temperature from the first found DS18x20 sensor every ↵second.  
2 # Author: Tony DiCola  
3 import time  
4  
5 import board  
6  
7 from adafruit_onewire.bus import OneWireBus  
8 from adafruit_ds18x20 import DS18X20  
9  
10  
11 # Initialize one-wire bus on board pin D5.  
12 ow_bus = OneWireBus(board.D5)  
13  
14 # Scan for sensors and grab the first one found.  
15 ds18 = DS18X20(ow_bus, ow_bus.scan()[0])  
16  
17 # Main loop to print the temperature every second.  
18 while True:  
19     print('Temperature: {:.3f}C'.format(ds18.temperature))  
20     time.sleep(1.0)
```

Listing 2: examples/ds18x20_asynctest.py

```
1 # Simple demo of printing the temperature from the first found DS18x20 sensor every ↵second.  
2 # Using the asynchronous functions start_temperature_read() and
```

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```
3 # read_temperature() to allow the main loop to keep processing while
4 # the conversion is in progress.
5 # Author: Louis Bertrand, based on original by Tony DiCola
6
7 import time
8
9 import board
10
11 from adafruit_onewire.bus import OneWireBus
12 from adafruit_ds18x20 import DS18X20
13
14
15 # Initialize one-wire bus on board pin D1.
16 ow_bus = OneWireBus(board.D1)
17
18 # Scan for sensors and grab the first one found.
19 ds18 = DS18X20(ow_bus, ow_bus.scan()[0])
20 ds18.resolution = 12
21
22 # Main loop to print the temperature every second.
23 while True:
24     conversion_delay = ds18.start_temperature_read()
25     conversion_ready_at = time.monotonic() + conversion_delay
26     print("waiting", end="")
27     while time.monotonic() < conversion_ready_at:
28         print(".", end="")
29         time.sleep(0.1)
30     print('\nTemperature: {:.3f}C\n'.format(ds18.read_temperature()))
31     time.sleep(1.0)
```

5.2 adafruit_ds18x20

Driver for Dallas 1-Wire temperature sensor.

- Author(s): Carter Nelson

class adafruit_ds18x20.DS18X20(bus, address)
Class which provides interface to DS18X20 temperature sensor.

read_temperature()

Read the temperature. No polling of the conversion busy bit (assumes that the conversion has completed).

resolution

The programmable resolution. 9, 10, 11, or 12 bits.

start_temperature_read()

Start asynchronous conversion, returns immediately. Returns maximum conversion delay [seconds] based on resolution.

temperature

The temperature in degrees Celsius.

CHAPTER 6

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