
Adafruit FXAS21002C Library Documentation

Release 1.0

Tony DiCola

Aug 23, 2019

Contents

1	Dependencies	3
2	Usage Example	5
3	Contributing	7
4	Building locally	9
4.1	Sphinx documentation	9
5	Table of Contents	11
5.1	Simple test	11
5.2	adafruit_fxas21002c	12
5.2.1	Implementation Notes	12
6	Indices and tables	13
	Python Module Index	15
	Index	17

CircuitPython module for the NXP FXAS21002C gyroscope.

CHAPTER 1

Dependencies

This driver depends on:

- [Adafruit CircuitPython](#)
- [Bus Device](#)

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the [Adafruit library and driver bundle](#).

CHAPTER 2

Usage Example

See `examples/simpletest.py` for an example of the usage.

CHAPTER 3

Contributing

Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.

CHAPTER 4

Building locally

To build this library locally you'll need to install the `circuitpython-build-tools` package.

```
python3 -m venv .env
source .env/bin/activate
pip install circuitpython-build-tools
```

Once installed, make sure you are in the virtual environment:

```
source .env/bin/activate
```

Then run the build:

```
circuitpython-build-bundles --filename_prefix adafruit-circuitpython-fxac21002c --
↳library_location .
```

4.1 Sphinx documentation

Sphinx is used to build the documentation based on rST files and comments in the code. First, install dependencies (feel free to reuse the virtual environment from above):

```
python3 -m venv .env
source .env/bin/activate
pip install Sphinx sphinx-rtd-theme
```

Now, once you have the virtual environment activated:

```
cd docs
sphinx-build -E -W -b html . _build/html
```

This will output the documentation to `docs/_build/html`. Open the `index.html` in your browser to view them. It will also (due to `-W`) error out on any warning like Travis will. This is a good way to locally verify it will pass.

5.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/fxas21002c_simpletest.py

```
1  # Simple demo of the FXAS21002C gyroscope.
2  # Will print the gyroscope values every second.
3  import time
4
5  import board
6  import busio
7
8  import adafruit_fxas21002c
9
10
11 # Initialize I2C bus and device.
12 i2c = busio.I2C(board.SCL, board.SDA)
13 sensor = adafruit_fxas21002c.FXAS21002C(i2c)
14 # Optionally create the sensor with a different gyroscope range (the
15 # default is 250 DPS, but you can use 500, 1000, or 2000 DPS values):
16 #sensor = adafruit_fxas21002c.FXAS21002C(i2c, gyro_range=adafruit_fxas21002c.GYRO_
17 ↪RANGE_500DPS)
18 #sensor = adafruit_fxas21002c.FXAS21002C(i2c, gyro_range=adafruit_fxas21002c.GYRO_
19 ↪RANGE_1000DPS)
20 #sensor = adafruit_fxas21002c.FXAS21002C(i2c, gyro_range=adafruit_fxas21002c.GYRO_
21 ↪RANGE_2000DPS)
22
23 # Main loop will read the gyroscope values every second and print them out.
24 while True:
25     # Read gyroscope.
26     gyro_x, gyro_y, gyro_z = sensor.gyroscope
27     # Print values.
```

(continues on next page)

(continued from previous page)

```

25     print('Gyroscope (radians/s): ({0:0.3f}, {1:0.3f}, {2:0.3f})'.format(gyro_x,
↪ gyro_y, gyro_z))
26     # Delay for a second.
27     time.sleep(1.0)

```

5.2 adafruit_fxas21002c

CircuitPython module for the NXP FXAS21002C gyroscope. Based on the driver from: https://github.com/adafruit/Adafruit_FXAS21002C

See examples/simpletest.py for a demo of the usage.

- Author(s): Tony DiCola

5.2.1 Implementation Notes

Hardware:

- Adafruit Precision NXP 9-DOF Breakout Board - FXOS8700 + FXAS21002 (Product ID: 3463)

Software and Dependencies:

- Adafruit CircuitPython firmware (2.2.0+) for the ESP8622 and M0-based boards: <https://github.com/adafruit/circuitpython/releases>
- Adafruit's Bus Device library: https://github.com/adafruit/Adafruit_CircuitPython_BusDevice

class `adafruit_fxas21002c.FXAS21002C` (*i2c*, *address=33*, *gyro_range=250*)

Driver for the NXP FXAS21002C gyroscope.

gyroscope

Read the gyroscope value and return its X, Y, Z axis values as a 3-tuple in radians/second.

read_raw()

Read the raw gyroscope readings. Returns a 3-tuple of X, Y, Z axis 16-bit signed values. If you want the gyroscope values in friendly units consider using the `gyroscope` property!

CHAPTER 6

Indices and tables

- `genindex`
- `modindex`
- `search`

a

adafruit_fxas21002c, [12](#)

A

`adafruit_fxas21002c` (*module*), [12](#)

F

`FXAS21002C` (*class in adafruit_fxas21002c*), [12](#)

G

`gyroscope` (*adafruit_fxas21002c.FXAS21002C* *attribute*), [12](#)

R

`read_raw()` (*adafruit_fxas21002c.FXAS21002C* *method*), [12](#)