
Adafruit GPS Library Documentation

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GPS parsing module. Can parse simple NMEA data sentences from serial GPS modules to read latitude, longitude, and more.

CHAPTER 1

Dependencies

This driver depends on:

- [Adafruit CircuitPython](#)

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the [Adafruit library and driver bundle](#).

CHAPTER 2

Usage Example

See `examples/simple.py` for a demonstration of parsing and printing GPS location.

CHAPTER 3

Contributing

Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.

CHAPTER 4

Building locally

To build this library locally you'll need to install the `circuitpython-build-tools` package.

```
python3 -m venv .env
source .env/bin/activate
pip install circuitpython-build-tools
```

Once installed, make sure you are in the virtual environment:

```
source .env/bin/activate
```

Then run the build:

```
circuitpython-build-bundles --filename_prefix adafruit-circuitpython-gps --library_
↳ location .
```

4.1 Sphinx documentation

Sphinx is used to build the documentation based on rST files and comments in the code. First, install dependencies (feel free to reuse the virtual environment from above):

```
python3 -m venv .env
source .env/bin/activate
pip install Sphinx sphinx-rtd-theme
```

Now, once you have the virtual environment activated:

```
cd docs
sphinx-build -E -W -b html . _build/html
```

This will output the documentation to `docs/_build/html`. Open the `index.html` in your browser to view them. It will also (due to `-W`) error out on any warning like Travis will. This is a good way to locally verify it will pass.

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5.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/gps_simpletest.py

```
1  # Simple GPS module demonstration.
2  # Will wait for a fix and print a message every second with the current location
3  # and other details.
4  import time
5  import board
6  import busio
7
8  import adafruit_gps
9
10
11 # Define RX and TX pins for the board's serial port connected to the GPS.
12 # These are the defaults you should use for the GPS FeatherWing.
13 # For other boards set RX = GPS module TX, and TX = GPS module RX pins.
14 RX = board.RX
15 TX = board.TX
16
17 # Create a serial connection for the GPS connection using default speed and
18 # a slightly higher timeout (GPS modules typically update once a second).
19 uart = busio.UART(TX, RX, baudrate=9600, timeout=3000)
20
21 # for a computer, use the pyserial library for uart access
22 #import serial
23 #uart = serial.Serial("/dev/ttyUSB0", baudrate=9600, timeout=3000)
24
25 # Create a GPS module instance.
26 gps = adafruit_gps.GPS(uart, debug=False)
27
```

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```

28 # Initialize the GPS module by changing what data it sends and at what rate.
29 # These are NMEA extensions for PMTK_314_SET_NMEA_OUTPUT and
30 # PMTK_220_SET_NMEA_UPDATERATE but you can send anything from here to adjust
31 # the GPS module behavior:
32 #   https://cdn-shop.adafruit.com/datasheets/PMTK_A11.pdf
33
34 # Turn on the basic GGA and RMC info (what you typically want)
35 gps.send_command(b'PMTK314,0,1,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0')
36 # Turn on just minimum info (RMC only, location):
37 #gps.send_command(b'PMTK314,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0')
38 # Turn off everything:
39 #gps.send_command(b'PMTK314,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0')
40 # Turn on everything (not all of it is parsed!)
41 #gps.send_command(b'PMTK314,1,1,1,1,1,1,0,0,0,0,0,0,0,0,0,0,0,0,0')
42
43 # Set update rate to once a second (1hz) which is what you typically want.
44 gps.send_command(b'PMTK220,1000')
45 # Or decrease to once every two seconds by doubling the millisecond value.
46 # Be sure to also increase your UART timeout above!
47 #gps.send_command(b'PMTK220,2000')
48 # You can also speed up the rate, but don't go too fast or else you can lose
49 # data during parsing. This would be twice a second (2hz, 500ms delay):
50 #gps.send_command(b'PMTK220,500')
51
52 # Main loop runs forever printing the location, etc. every second.
53 last_print = time.monotonic()
54 while True:
55     # Make sure to call gps.update() every loop iteration and at least twice
56     # as fast as data comes from the GPS unit (usually every second).
57     # This returns a bool that's true if it parsed new data (you can ignore it
58     # though if you don't care and instead look at the has_fix property).
59     gps.update()
60     # Every second print out current location details if there's a fix.
61     current = time.monotonic()
62     if current - last_print >= 1.0:
63         last_print = current
64         if not gps.has_fix:
65             # Try again if we don't have a fix yet.
66             print('Waiting for fix...')
67             continue
68         # We have a fix! (gps.has_fix is true)
69         # Print out details about the fix like location, date, etc.
70         print('=' * 40) # Print a separator line.
71         print('Fix timestamp: {}/{}/{} {:02}:{:02}:{:02}'.format(
72             gps.timestamp_utc.tm_mon, # Grab parts of the time from the
73             gps.timestamp_utc.tm_mday, # struct_time object that holds
74             gps.timestamp_utc.tm_year, # the fix time. Note you might
75             gps.timestamp_utc.tm_hour, # not get all data like year, day,
76             gps.timestamp_utc.tm_min, # month!
77             gps.timestamp_utc.tm_sec))
78         print('Latitude: {0:.6f} degrees'.format(gps.latitude))
79         print('Longitude: {0:.6f} degrees'.format(gps.longitude))
80         print('Fix quality: {}'.format(gps.fix_quality))
81         # Some attributes beyond latitude, longitude and timestamp are optional
82         # and might not be present. Check if they're None before trying to use!
83         if gps.satellites is not None:
84             print('# satellites: {}'.format(gps.satellites))

```

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```

85     if gps.altitude_m is not None:
86         print('Altitude: {} meters'.format(gps.altitude_m))
87     if gps.track_angle_deg is not None:
88         print('Speed: {} knots'.format(gps.speed_knots))
89     if gps.track_angle_deg is not None:
90         print('Track angle: {} degrees'.format(gps.track_angle_deg))
91     if gps.horizontal_dilution is not None:
92         print('Horizontal dilution: {}'.format(gps.horizontal_dilution))
93     if gps.height_geoid is not None:
94         print('Height geo ID: {} meters'.format(gps.height_geoid))

```

5.2 adafruit_gps

GPS parsing module. Can parse simple NMEA data sentences from serial GPS modules to read latitude, longitude, and more.

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5.2.1 Implementation Notes

Hardware:

- Adafruit [Ultimate GPS Breakout](#)
- Adafruit [Ultimate GPS FeatherWing](#)

Software and Dependencies:

- Adafruit CircuitPython firmware for the ESP8622 and M0-based boards: <https://github.com/adafruit/circuitpython/releases>

class `adafruit_gps.GPS` (*uart, debug=False*)

GPS parsing module. Can parse simple NMEA data sentences from serial GPS modules to read latitude, longitude, and more.

datetime

Return struct_time object to feed `rtc.set_time_source()` function

has_fix

True if a current fix for location information is available.

send_command (*command, add_checksum=True*)

Send a command string to the GPS. If `add_checksum` is True (the default) a NMEA checksum will automatically be computed and added. Note you should NOT add the leading \$ and trailing * to the command as they will automatically be added!

update ()

Check for updated data from the GPS module and process it accordingly. Returns True if new data was processed, and False if nothing new was received.

CHAPTER 6

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