
AdafruitMCP230xx Library Documentation

Release 1.0

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Jan 22, 2021

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CircuitPython module for the MCP23017 and MCP23008 I2C I/O extenders.

CHAPTER 1

Dependencies

This driver depends on:

- [Adafruit CircuitPython](#)
- [Bus Device](#)

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the [Adafruit library and driver bundle](#).

CHAPTER 2

Installing from PyPI

On supported GNU/Linux systems like the Raspberry Pi, you can install the driver locally [from PyPI](#). To install for current user:

```
pip3 install adafruit-circuitpython-mcp230xx
```

To install system-wide (this may be required in some cases):

```
sudo pip3 install adafruit-circuitpython-mcp230xx
```

To install in a virtual environment in your current project:

```
mkdir project-name && cd project-name
python3 -m venv .env
source .env/bin/activate
pip3 install adafruit-circuitpython-mcp230xx
```


CHAPTER 3

Usage Example

See `examples/mcp230xx_simpletest.py` for a demo of the usage.

CHAPTER 4

Contributing

Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.

CHAPTER 5

Documentation

For information on building library documentation, please check out [this guide](#).

6.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/mcp230xx_simpletest.py

```
1  # SPDX-FileCopyrightText: 2017 Tony DiCola for Adafruit Industries
2  #
3  # SPDX-License-Identifier: MIT
4
5  # Simple demo of reading and writing the digital I/O of the MCP2300xx as if
6  # they were native CircuitPython digital inputs/outputs.
7  # Author: Tony DiCola
8  import time
9
10 import board
11 import busio
12 import digitalio
13
14 from adafruit_mcp230xx.mcp23008 import MCP23008
15
16 # from adafruit_mcp230xx.mcp23017 import MCP23017
17
18
19 # Initialize the I2C bus:
20 i2c = busio.I2C(board.SCL, board.SDA)
21
22 # Create an instance of either the MCP23008 or MCP23017 class depending on
23 # which chip you're using:
24 mcp = MCP23008(i2c) # MCP23008
25 # mcp = MCP23017(i2c) # MCP23017
26
27 # Optionally change the address of the device if you set any of the A0, A1, A2
```

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```

28 # pins. Specify the new address with a keyword parameter:
29 # mcp = MCP23017(i2c, address=0x21) # MCP23017 w/ A0 set
30
31 # Now call the get_pin function to get an instance of a pin on the chip.
32 # This instance will act just like a digitalio.DigitalInOut class instance
33 # and has all the same properties and methods (except you can't set pull-down
34 # resistors, only pull-up!). For the MCP23008 you specify a pin number from 0
35 # to 7 for the GP0...GP7 pins. For the MCP23017 you specify a pin number from
36 # 0 to 15 for the GPIOA0...GPIOA7, GPIOB0...GPIOB7 pins (i.e. pin 12 is GPIOB4).
37 pin0 = mcp.get_pin(0)
38 pin1 = mcp.get_pin(1)
39
40 # Setup pin0 as an output that's at a high logic level.
41 pin0.switch_to_output(value=True)
42
43 # Setup pin1 as an input with a pull-up resistor enabled. Notice you can also
44 # use properties to change this state.
45 pin1.direction = digitalio.Direction.INPUT
46 pin1.pull = digitalio.Pull.UP
47
48 # Now loop blinking the pin 0 output and reading the state of pin 1 input.
49 while True:
50     # Blink pin 0 on and then off.
51     pin0.value = True
52     time.sleep(0.5)
53     pin0.value = False
54     time.sleep(0.5)
55     # Read pin 1 and print its state.
56     print("Pin 1 is at a high level: {}".format(pin1.value))

```

6.2 mcp230xx

CircuitPython module for the MCP23017 and MCP23008 I2C I/O extenders.

- Author(s): Tony DiCola

class adafruit_mcp230xx.mcp230xx.**MCP230XX**(i2c, address)
Base class for MCP230xx devices.

6.3 mcp23008

CircuitPython module for the MCP23008 I2C I/O extenders.

- Author(s): Tony DiCola

class adafruit_mcp230xx.mcp23008.**MCP23008**(i2c, address=<sphinx.ext.autodoc.importer._MockObject object>, reset=True)
Supports MCP23008 instance on specified I2C bus and optionally at the specified I2C address.

get_pin(pin)
Convenience function to create an instance of the DigitalInOut class pointing at the specified pin of this MCP23008 device.

gpio

The raw GPIO output register. Each bit represents the output value of the associated pin (0 = low, 1 = high), assuming that pin has been configured as an output previously.

gppu

The raw GPPU pull-up register. Each bit represents if a pull-up is enabled on the specified pin (1 = pull-up enabled, 0 = pull-up disabled). Note pull-down resistors are NOT supported!

iodir

The raw IODIR direction register. Each bit represents direction of a pin, either 1 for an input or 0 for an output mode.

6.4 mcp23017

CircuitPython module for the MCP23017 I2C I/O extenders.

- Author(s): Tony DiCola

class adafruit_mcp230xx.mcp23017.**MCP23017** (*i2c, address=<sphinx.ext.autodoc.importer._MockObject object>, reset=True*)

Supports MCP23017 instance on specified I2C bus and optionally at the specified I2C address.

clear_inta()

Clears port A interrupts.

clear_intb()

Clears port B interrupts.

clear_ints()

Clears interrupts by reading INTCAP.

default_value

The raw DEFVAL interrupt control register. The default comparison value is configured in the DEFVAL register. If enabled (via GPINTEN and INTCON) to compare against the DEFVAL register, an opposite value on the associated pin will cause an interrupt to occur.

get_pin(pin)

Convenience function to create an instance of the DigitalInOut class pointing at the specified pin of this MCP23017 device.

gpio

The raw GPIO output register. Each bit represents the output value of the associated pin (0 = low, 1 = high), assuming that pin has been configured as an output previously.

gpioa

The raw GPIO A output register. Each bit represents the output value of the associated pin (0 = low, 1 = high), assuming that pin has been configured as an output previously.

gpiob

The raw GPIO B output register. Each bit represents the output value of the associated pin (0 = low, 1 = high), assuming that pin has been configured as an output previously.

gppu

The raw GPPU pull-up register. Each bit represents if a pull-up is enabled on the specified pin (1 = pull-up enabled, 0 = pull-up disabled). Note pull-down resistors are NOT supported!

gppua

The raw GPPU A pull-up register. Each bit represents if a pull-up is enabled on the specified pin (1 = pull-up enabled, 0 = pull-up disabled). Note pull-down resistors are NOT supported!

gppub

The raw GPPU B pull-up register. Each bit represents if a pull-up is enabled on the specified pin (1 = pull-up enabled, 0 = pull-up disabled). Note pull-down resistors are NOT supported!

int_flag

Returns a list with the pin numbers that caused an interrupt port A → pins 0-7 port B → pins 8-15

int_flaga

Returns a list of pin numbers that caused an interrupt in port A pins: 0-7

int_flagb

Returns a list of pin numbers that caused an interrupt in port B pins: 8-15

interrupt_configuration

The raw INTCON interrupt control register. The INTCON register controls how the associated pin value is compared for the interrupt-on-change feature. If a bit is set, the corresponding I/O pin is compared against the associated bit in the DEFVAL register. If a bit value is clear, the corresponding I/O pin is compared against the previous value.

interrupt_enable

The raw GPINTEN interrupt control register. The GPINTEN register controls the interrupt-on-change feature for each pin. If a bit is set, the corresponding pin is enabled for interrupt-on-change. The DEFVAL and INTCON registers must also be configured if any pins are enabled for interrupt-on-change.

io_control

The raw IOCON configuration register. Bit 1 controls interrupt polarity (1 = active-high, 0 = active-low). Bit 2 is whether irq pin is open drain (1 = open drain, 0 = push-pull). Bit 3 is unused. Bit 4 is whether SDA slew rate is enabled (1 = yes). Bit 5 is if I2C address pointer auto-increments (1 = no). Bit 6 is whether interrupt pins are internally connected (1 = yes). Bit 7 is whether registers are all in one bank (1 = no).

ioidir

The raw IODIR direction register. Each bit represents direction of a pin, either 1 for an input or 0 for an output mode.

ioidira

The raw IODIR A direction register. Each bit represents direction of a pin, either 1 for an input or 0 for an output mode.

ioidirb

The raw IODIR B direction register. Each bit represents direction of a pin, either 1 for an input or 0 for an output mode.

ipol

The raw IPOL output register. Each bit represents the polarity value of the associated pin (0 = normal, 1 = inverted), assuming that pin has been configured as an input previously.

ipola

The raw IPOL A output register. Each bit represents the polarity value of the associated pin (0 = normal, 1 = inverted), assuming that pin has been configured as an input previously.

ipolb

The raw IPOL B output register. Each bit represents the polarity value of the associated pin (0 = normal, 1 = inverted), assuming that pin has been configured as an input previously.

6.5 digital_inout

Digital input/output of the MCP230xx.

- Author(s): Tony DiCola

class `adafruit_mcp230xx.digital_inout.DigitalInOut` (*pin_number*, *mcp230xx*)

Digital input/output of the MCP230xx. The interface is exactly the same as the `digitalio.DigitalInOut` class, however:

- MCP230xx family does not support pull-down resistors;
- MCP23016 does not support pull-up resistors.

Exceptions will be thrown when attempting to set unsupported pull configurations.

direction

The direction of the pin, either `True` for an input or `False` for an output.

invert_polarity

The polarity of the pin, either `True` for an Inverted or `False` for an normal.

pull

Enable or disable internal pull-up resistors for this pin. A value of `digitalio.Pull.UP` will enable a pull-up resistor, and `None` will disable it. Pull-down resistors are NOT supported!

switch_to_input (*pull=None*, *invert_polarity=False*, ***kwargs*)

Switch the pin state to a digital input with the provided starting pull-up resistor state (optional, no pull-up by default) and input polarity. Note that pull-down resistors are NOT supported!

switch_to_output (*value=False*, ***kwargs*)

Switch the pin state to a digital output with the provided starting value (`True/False` for high or low, default is `False/low`).

value

The value of the pin, either `True` for high or `False` for low. Note you must configure as an output or input appropriately before reading and writing this value.

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