Adafruit MPR121 Library Documentation

Release 1.0

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Contents

Adafruit CircuitPython module for the MPR121 capacitive touch breakout board.

CHAPTER 1

Dependencies

This driver depends on:

- Adafruit CircuitPython
- Bus Device

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the Adafruit library and driver bundle.

CHAPTER 2

Installing from PyPI

On supported GNU/Linux systems like the Raspberry Pi, you can install the driver locally from PyPI. To install for current user:

```
pip3 install adafruit-circuitpython-mpr121
```

To install system-wide (this may be required in some cases):

```
sudo pip3 install adafruit-circuitpython-mpr121
```

To install in a virtual environment in your current project:

```
mkdir project-name && cd project-name
python3 -m venv .env
source .env/bin/activate
pip3 install adafruit-circuitpython-mpr121
```

CHAPTER 3

Usage Example

See usage in the examples/mpr121_simpletest.py file.

CHAPTER 4

Contributing

Contributions are welcome! Please read our Code of Conduct before contributing to help this project stay welcoming.

CHAPTER 5

Documentation

For information on building library documentation, please check out this guide.

CHAPTER 6

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6.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/mpr121_simpletest.py

```
# Simple test of the MPR121 capacitive touch sensor library.
# Will print out a message when any of the 12 capacitive touch inputs of the
# board are touched.  Open the serial REPL after running to see the output.
# Author: Tony DiCola
import time
import board
import busio

# Import MPR121 module.
import adafruit_mpr121

# Create I2C bus.
i2c = busio.I2C(board.SCL, board.SDA)

# Create MPR121 object.
mpr121 = adafruit_mpr121.MPR121(i2c)

# Note you can optionally change the address of the device:
# mpr121 = adafruit_mpr121.MPR121(i2c, address=0x91)

# Loop forever testing each input and printing when they're touched.
while True:
    # Loop through all 12 inputs (0-11).
    for i in range(12):
        # Call is_touched and pass it then number of the input.  If it's touched
        # it will return True, otherwise it will return False.
        if mpr121[i].value:
```

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```
            print("Input {} touched!".format(i))
    time.sleep(0.25)  # Small delay to keep from spamming output messages.
```

Listing 2: examples/mpr121_piano.py

```
# MPR121 piano demo.
# Listens to the first 7 inputs of the MPR121 and plays a middle scale note
# when an input is touched.  Note only one note is played at a time!
# For use with microcontrollers or computers with PWM support only!
# Author: Tony DiCola
# Modified by: Carter Nelson

import board
import busio
import pulseio

# Import MPR121 module.
import adafruit_mpr121


# Configure PWM buzzer and other state:
BUZZER_PIN = board.D9
TONE_ON_DUTY = 2 ** 15  # Duty cycle of tone when turned on, a square wave.
TONE_OFF_DUTY = 0  # Duty cycle of tone when turned off, 0 or no signal.
NOTE_FREQS = [
    261,  # Input 0 = 261 hz = middle C
    294,  # Input 1 = middle D
    329,  # Input 2 = middle E
    349,  # Input 3 = middle F
    392,  # Input 4 = middle G
    440,  # Input 5 = middle A
    493,  # Input 6 = middle B
    0,  # Input 7 = nothing (set to a frequency in hertz!)
    0,  # Input 8
    0,  # Input 9
    0,  # Input 10
    0,
]  # Input 11


# Create I2C bus.
i2c = busio.I2C(board.SCL, board.SDA)

# Create MPR121 class.
mpr121 = adafruit_mpr121.MPR121(i2c)
# Note you can optionally change the address of the device:
# mpr121 = adafruit_mpr121.MPR121(i2c, address=0x91)

# pylint: disable-msg=no-member
# Setup buzzer PWM output.
buzzer = pulseio.PWMOut(
    BUZZER_PIN, duty_cycle=TONE_OFF_DUTY, frequency=440, variable_frequency=True
)
# pylint: disable-msg=no-member

last_note = None
```

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```
while True:
    # Get touched state for all pins
    touched = mpr121.touched_pins
    # If no pins are touched, be quiet
    if True not in touched:
        last_note = None
        buzzer.duty_cycle = TONE_OFF_DUTY
        continue
    # Get index of touched pin
    note = touched.index(True)
    # Play note if pin is different and has a defined note
    if note != last_note and NOTE_FREQS[note] != 0:
        last_note = note
        buzzer.frequency = NOTE_FREQS[note]
        buzzer.duty_cycle = TONE_ON_DUTY
```

6.2 adafruit_mpr121

CircuitPython driver for the MPR121 capacitive touch breakout board.

See usage in the examples/simpletest.py file.

- Author(s): Tony DiCola

6.2.1 Implementation Notes

Hardware:

- Adafruit 12-Key Capacitive Touch Sensor Breakout - MPR121 (Product ID: 1982)
- Adafruit 12 x Capacitive Touch Shield for Arduino - MPR121 (Product ID: 2024)

Software and Dependencies:

- Adafruit CircuitPython firmware for the ESP8622 and M0-based boards: https://github.com/adafruit/circuitpython/releases
- Adafruit's Bus Device library: https://github.com/adafruit/Adafruit_CircuitPython_BusDevice

class adafruit_mpr121.**MPR121**(*i2c*, *address=90*)
Driver for the MPR121 capacitive touch breakout board.

baseline_data(*pin*)
Return baseline data register value for the provided pin (0-11). Useful for debugging.

filtered_data(*pin*)
Return filtered data register value for the provided pin (0-11). Useful for debugging.

is_touched(*pin*)
Return True if the specified pin is being touched, otherwise returns False.

reset()
Reset the MPR121 into a default state ready to detect touch inputs.

touched()
Return touch state of all pins as a 12-bit value where each bit represents a pin, with a value of 1 being touched and 0 not being touched.

touched_pins
A tuple of touched state for all pins.

class adafruit_mpr121.**MPR121_Channel**(*mpr121*, *channel*)
Helper class to represent a touch channel on the MPR121. Not meant to be used directly.

raw_value
The raw touch measurement.

release_threshold
The release threshold.

threshold
The touch threshold.

value
Whether the touch pad is being touched or not.

CHAPTER 7

Indices and tables

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Python Module Index

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