
Adafruit PCA9685 Library Documentation

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Driver for the PCA9685, a 16-channel, 12-bit PWM chip

CHAPTER 1

Dependencies

This driver depends on:

- [Adafruit CircuitPython](#)
- [Bus Device](#)
- [Register](#)

Please ensure all dependencies are available on the CircuitPython filesystem. This is easily achieved by downloading the [Adafruit library and driver bundle](#).

CHAPTER 2

Installing from PyPI

On supported GNU/Linux systems like the Raspberry Pi, you can install the driver locally [from PyPI](#). To install for current user:

```
pip3 install adafruit-circuitpython-pca9685
```

To install system-wide (this may be required in some cases):

```
sudo pip3 install adafruit-circuitpython-pca9685
```

To install in a virtual environment in your current project:

```
mkdir project-name && cd project-name
python3 -m venv .env
source .env/bin/activate
pip3 install adafruit-circuitpython-pca9685
```


CHAPTER 3

Usage Example

See `examples/pca9685_simpletest.py` for a demo of the usage.

CHAPTER 4

Contributing

Contributions are welcome! Please read our [Code of Conduct](#) before contributing to help this project stay welcoming.

CHAPTER 5

Documentation

For information on building library documentation, please check out [this guide](#).

6.1 Simple test

Ensure your device works with this simple test.

Listing 1: examples/pca9685_simpletest.py

```
1  # This simple test outputs a 50% duty cycle PWM single on the 0th channel. Connect an_
   ↳ LED and
2  # resistor in series to the pin to visualize duty cycle changes and its impact on_
   ↳ brightness.
3
4  from board import SCL, SDA
5  import busio
6
7  # Import the PCA9685 module.
8  from adafruit_pca9685 import PCA9685
9
10 # Create the I2C bus interface.
11 i2c_bus = busio.I2C(SCL, SDA)
12
13 # Create a simple PCA9685 class instance.
14 pca = PCA9685(i2c_bus)
15
16 # Set the PWM frequency to 60hz.
17 pca.frequency = 60
18
19 # Set the PWM duty cycle for channel zero to 50%. duty_cycle is 16 bits to match_
   ↳ other PWM objects
20 # but the PCA9685 will only actually give 12 bits of resolution.
21 pca.channels[0].duty_cycle = 0x7FFF
```

Listing 2: examples/pca9685_calibration.py

```

1  # This advanced example can be used to compute a more precise reference_clock_speed.
   ↳ Use an
2  # oscilloscope or logic analyzer to measure the signal frequency and type the results.
   ↳ into the
3  # prompts. At the end it'll give you a more precise value around 25 mhz for your
   ↳ reference clock
4  # speed.
5
6  import time
7
8  from board import SCL, SDA
9  import busio
10
11 # Import the PCA9685 module.
12 from adafruit_pca9685 import PCA9685
13
14 # Create the I2C bus interface.
15 i2c_bus = busio.I2C(SCL, SDA)
16
17 # Create a simple PCA9685 class instance.
18 pca = PCA9685(i2c_bus)
19
20 # Set the PWM frequency to 100hz.
21 pca.frequency = 100
22
23 input("Press enter when ready to measure default frequency.")
24
25 # Set the PWM duty cycle for channel zero to 50%. duty_cycle is 16 bits to match
   ↳ other PWM objects
26 # but the PCA9685 will only actually give 12 bits of resolution.
27 print("Running with default calibration")
28 pca.channels[0].duty_cycle = 0x7FFF
29 time.sleep(1)
30 pca.channels[0].duty_cycle = 0
31
32 measured_frequency = float(input("Frequency measured: "))
33 print()
34
35 pca.reference_clock_speed = pca.reference_clock_speed * (
36     measured_frequency / pca.frequency
37 )
38 # Set frequency again so we can get closer. Reading it back will produce the real
   ↳ value.
39 pca.frequency = 100
40
41 input("Press enter when ready to measure coarse calibration frequency.")
42 pca.channels[0].duty_cycle = 0x7FFF
43 time.sleep(1)
44 pca.channels[0].duty_cycle = 0
45 measured_after_calibration = float(input("Frequency measured: "))
46 print()
47
48 reference_clock_speed = measured_after_calibration * 4096 * pca.prescale_reg
49
50 print("Real reference clock speed: {0:.0f}".format(reference_clock_speed))

```

Listing 3: examples/pca9685_servo.py

```

1  # This example moves a servo its full range (180 degrees by default) and then back.
2
3  from board import SCL, SDA
4  import busio
5
6  # Import the PCA9685 module.
7  from adafruit_pca9685 import PCA9685
8
9  # This example also relies on the Adafruit motor library available here:
10 # https://github.com/adafruit/Adafruit_CircuitPython_Motor
11 from adafruit_motor import servo
12
13 i2c = busio.I2C(SCL, SDA)
14
15 # Create a simple PCA9685 class instance.
16 pca = PCA9685(i2c)
17 pca.frequency = 50
18
19 # To get the full range of the servo you will likely need to adjust the min_pulse and
20 # ↪ max_pulse to
21 # match the stall points of the servo.
22 # This is an example for the Sub-micro servo: https://www.adafruit.com/product/2201
23 # servo7 = servo.Servo(pca.channels[7], min_pulse=580, max_pulse=2480)
24 # This is an example for the Micro Servo - High Powered, High Torque Metal Gear:
25 # https://www.adafruit.com/product/2307
26 # servo7 = servo.Servo(pca.channels[7], min_pulse=600, max_pulse=2400)
27 # This is an example for the Standard servo - TowerPro SG-5010 - 5010:
28 # https://www.adafruit.com/product/155
29 # servo7 = servo.Servo(pca.channels[7], min_pulse=600, max_pulse=2500)
30 # This is an example for the Analog Feedback Servo: https://www.adafruit.com/product/
31 # ↪ 1404
32 # servo7 = servo.Servo(pca.channels[7], min_pulse=600, max_pulse=2600)
33
34 # The pulse range is 1000 - 2000 by default.
35 servo7 = servo.Servo(pca.channels[7])
36
37 for i in range(180):
38     servo7.angle = i
39 for i in range(180):
40     servo7.angle = 180 - i
41
42 pca.deinit()

```

6.2 adafruit_pca9685

Driver for the PCA9685 PWM control IC. Its commonly used to control servos, leds and motors.

See also:

The [Adafruit CircuitPython Motor library](#) can be used to control the PWM outputs for specific uses instead of generic duty_cycle adjustments.

- Author(s): Scott Shawcroft

6.2.1 Implementation Notes

Hardware:

- Adafruit 16-Channel 12-bit PWM/Servo Driver - I2C interface - PCA9685 (Product ID: 815)

Software and Dependencies:

- Adafruit CircuitPython firmware for the ESP8622 and M0-based boards: <https://github.com/adafruit/circuitpython/releases>
- Adafruit's Bus Device library: https://github.com/adafruit/Adafruit_CircuitPython_BusDevice
- Adafruit's Register library: https://github.com/adafruit/Adafruit_CircuitPython_Register

class `adafruit_pca9685.PCA9685` (*i2c_bus*, *, *address*=64, *reference_clock_speed*=25000000)
Initialise the PCA9685 chip at address on *i2c_bus*.

The internal reference clock is 25mhz but may vary slightly with environmental conditions and manufacturing variances. Providing a more precise *reference_clock_speed* can improve the accuracy of the frequency and duty_cycle computations. See the `calibration.py` example for how to derive this value by measuring the resulting pulse widths.

Parameters

- ***i2c_bus*** (*I2C*) – The I2C bus which the PCA9685 is connected to.
- ***address*** (*int*) – The I2C address of the PCA9685.
- ***reference_clock_speed*** (*int*) – The frequency of the internal reference clock in Hertz.

channels = None

Sequence of 16 *PWMChannel* objects. One for each channel.

deinit ()

Stop using the pca9685.

frequency

The overall PWM frequency in Hertz.

reference_clock_speed = None

The reference clock speed in Hz.

reset ()

Reset the chip.

class `adafruit_pca9685.PCAChannels` (*pca*)

Lazily creates and caches channel objects as needed. Treat it like a sequence.

class `adafruit_pca9685.PWMChannel` (*pca*, *index*)

A single PCA9685 channel that matches the *PWMOut* API.

duty_cycle

16 bit value that dictates how much of one cycle is high (1) versus low (0). 0xffff will always be high, 0 will always be low and 0x7fff will be half high and then half low.

frequency

The overall PWM frequency in Hertz (read-only). A *PWMChannel*'s frequency cannot be set individually. All channels share a common frequency, set by *PCA9685.frequency*.

CHAPTER 7

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